	٩w	10	
•			
	12	.)	
		W Ø	are given
		f	$(s,t)$ = $(b + \alpha \cos s) \cos t$
		۴	$(s,t)=(b+\alpha \cos s)sint$
			$(s,t) = c_{1} s_{1} s_{2}$
		wit	h
		f	$(s,t) = (f_1(s,t), f_2(s,t), f_3(s,t))$
		Since	$sup \in (os) = sup \in sin = 1$ , $inf \in (os) = inf \notin sin = -1$
			range of K is $([-b-a, b+a], [-b-a, b+a], [-a, a])$
		9)	we first find that
			$\nabla f_1(s,t) = (-\alpha \sin s \cos t) - (b + \alpha \cos s) \sin t$
			This is o When
			(2) $(b + a \cos s) \sin t = 0$
			for @ This happens when sins = 0 or cos t=0
			and for @ when sint=0. When Sint=0, cost70, so
			for O sins = 0 is the only option. These hold when
			t= 0 or t= π, s=0 or s= π, for all those values
			$f_2(s, t) = f_2(s, t) = 0$ fully, the paints are
			$P_{1} = \begin{pmatrix} p + a \\ 0 \end{pmatrix}, P_{2} \subseteq \begin{pmatrix} p - a \\ 0 \end{pmatrix}, P_{3} \subseteq \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_{3} \subseteq \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_{4} E \end{pmatrix},$

by we first find that

 $\nabla f(s,t) = (\alpha \cos s, o)$ Thus  $\nabla_3 f(s,t) = 0$  when  $\cos s = 0$  so  $s = (\frac{1}{2} + k) T$   $k \in \mathbb{N}$ for all s fr(s,t)=0. Since t is still variable, f, (s, t) and f, (s, t) can have all values in the range Thus for all q E[-bcost, bcost] x [-bsint, bsint] x E-av, a 3,  $t \in [0, 2 \times \Pi], \nabla f_{2} (f^{-1}(q)) = 0$ 

- c) We have
  - $f_1(s,t) = [b + \alpha \cos s) \cos t$
  - $\nabla f_1(s,t) = (-\alpha \sin s \cos t) (b + \alpha \cos s) \sin t$
  - we found the points
    - $P_{1} = \begin{pmatrix} b + a \\ 0 \\ a \end{pmatrix} \quad P_{2} \subset \begin{bmatrix} b a \\ 0 \\ 0 \end{bmatrix} \quad P_{3} \subset \begin{bmatrix} -b + a \\ 0 \\ 0 \end{bmatrix} \quad P_{4} \subset \begin{bmatrix} -b a \\ 0 \\ 0 \end{bmatrix}$
  - At these points we have to or t= TI S=0 or S= T
  - at too lost will only decrease with a change in t.
  - ton it will only increase. For both, Sin changes in at the same direction as t. This also holds for \$50 and
  - s= T, Given b>a>0, so f(0,0)> f(0, T) and
  - E(TT, 0) < f(TT, TT). By the above, sin will flip sign,
  - so f(0,0) is a local maximum f(TT, TT) is a local minimum
  - and first, and florts) are saddle points.
  - Since The points are on the boundary only they

nood to be cars idered (Maximum Value Theorem)

13)  
Let 
$$f': R^{1} \rightarrow R^{3}$$
 be differentiable, and  $|f(t)| = 1 \quad \forall t$ ,  
 $h(t) = f(t) f(t) = f(t)^{2} = |f(t)|^{2} = 1$ 

Then

h(b) = f(1) f(b) + f(b) f(b) = 0

so f'(t)f(t) = 0

Geometrically since  $|f(t)| = \sqrt{f_1(t)} + f_2(t)^2 + f_3(t)^2}$  we would we can think of f(t) as mapping a value to a point on a unit sphere in 3D space. Since f is diff  $\Rightarrow$  cont this mapping is a continuous curve on the surface. Think of f'(t) as the normal vector to a point on the sphere f(t).

14,

we have the equations.  $x+y+t^2=0$ ()  $3x + y - z + w^2 = 0$ 2 x + 3 y - 2 = 0 0 x - y + 27+ w = 0 1 2x + 2y - 37 + 2w = 0 y = - 2x+z x -2x+7+2=0 =-3x+2+2 we can write this as  $f_1(x,y,z;u) = 3x + y - z + u^2$ x = 2 + 22  $-3(\frac{1}{3}7 + \frac{1}{3}2) + 7 + 2 = 0$ f(x,y,z,u) = x - y + 2z + uf(x,y,z;u)=2x + 2y - 32 + 2n with  $f=(f_1, f_2, f_3)$ . We now with for solve for f(x, y, z, u) = 0in terms of different variables for this the implicit

function theorem comes in handy. By Rudin (f like his version better) we can solve f(X, y, 2, u) = (0, 0, 0, 0) in terms of X, y, 2, or u if conditions are met. Letthe variables we solve for be h and lot the term $be k. Then if <math>A_h = A(h, 0)$  is invertible. We can write f(X, y, 2, h) as

$$f(x, y, z, u) = \begin{pmatrix} 3 & | & -1 & zu \\ 1 & -1 & z & 1 \\ z & z & -3 & z \end{pmatrix} \begin{pmatrix} y \\ y \\ z \\ u \end{pmatrix} = A \cup v^{-1}(x, y, z, u)^{T}$$

we see that for  $h_{2}(X, y, u) = h_{2}(X, z, w)$ , and  $h_{2}(Y, z, u)$ . The submatrix  $A_{1}$  has non-zero determinant (Thank you Maple) for  $u \neq \frac{3}{2}$ , for  $h_{2}(X, y, z) = det(A_{1}) = 0$ , so by the implicit function theorem we can not solve with u, but we can for X, Y, Z

## Puzh 14

Monestly i don't even know where bo begin with this question. My guess was to use Characterization of diagonalizable matrizes by linear independent eigenvectors But even with this I do not know how to proceed t mill ask around and see is any one has any ideas and correct my work if figet faedback 24) we have

$$\int (x,y) = \begin{cases} \frac{xy(x'-y')}{x^{2}+y^{2}} & (x,y)\neq 0.0 \end{cases}$$

$$\bigcup \quad \text{else}$$

for hER, So f is cont on R. Now. Since

$$\frac{\partial f}{\partial x} = \frac{y(x^{4} + 4x^{2}y^{2} - y^{4})}{(x^{2} + y^{2})^{2}} \qquad \qquad \frac{\partial f}{\partial y} = \frac{\chi(x^{4} - 4x^{2}y^{2} - y^{4})}{(x^{2} + y^{2})^{2}} \qquad \qquad f(0,0) = 0$$

$$\lim_{x \to 0} \frac{\partial f}{\partial x}(0,0) = \lim_{x \to 0} \frac{\partial f}{\partial y}(0,0) = \lim_{x \to 0} \frac{\partial f}{\partial x}(th,t) = \lim_{x \to 0} \frac{\partial f}{\partial y}(th,t) = 0$$

so Partial derivatives are continuous and differentiable, meaning second durivative exists, so partial ones do as well. But

$$\frac{\partial}{\partial x \partial y} \frac{f}{h \partial x} (0,0) = \lim_{h \to 0} \frac{f_x(0,0+h) - f_y(0,0)}{h} = \lim_{h \to 0} \frac{h}{h} = -1$$

$$\frac{\partial}{\partial y \partial x} \frac{f_y(0,0)}{h \partial x \partial y} = \lim_{h \to 0} \frac{f_y(0+h,0) - f_y(0,0)}{h} = \lim_{h \to 0} \frac{h}{h} = 1$$

$$\int_{h \to 0} \frac{h}{h \partial x \partial y} \frac{f_y(0,0)}{h} = \int_{h \to 0} \frac{h}{h} = 1$$