

MW 11

1. Consider the following forms on $\mathbb{R}^n \setminus \{0\}$:

- 2-form: $\Omega_1 = |x|^{-2} (x_1 dx_2 - x_2 dx_1)$

- 3-form: $\Omega_2 = |x|^{-3} (x_1 dx_2 \wedge dx_3 - x_2 dx_1 \wedge dx_3 + x_3 dx_1 \wedge dx_2)$

First we wds that $d\Omega_1 = 0$. We note that

$$|x|^{-2} = \sqrt{x_1^2 + x_2^2}^{-2} = \frac{1}{x_1^2 + x_2^2}$$

$$d\Omega_1 = d(|x|^{-2} (x_1 dx_2 - x_2 dx_1))$$

$$= d\left(\frac{1}{x_1^2 + x_2^2} (x_1 dx_2 - x_2 dx_1)\right)$$

$$= d\left(\frac{x_1}{x_1^2 + x_2^2}\right) \wedge dx_2 - d\left(\frac{x_2}{x_1^2 + x_2^2}\right) \wedge dx_1$$

$$\text{with } f(x, y) = \frac{x_1}{x_1^2 + x_2^2}, \quad g(x_1, x_2) = \frac{x_2}{x_1^2 + x_2^2}$$

$$= df \wedge dx_2 - dg \wedge dx_1$$

$$= \frac{\partial f}{\partial x_1} dx_1 \wedge dx_2 - \frac{\partial g}{\partial x_2} dx_2 \wedge dx_1 \quad (\text{Two terms cancel by } dx_i \wedge dx_i = 0)$$

$$= \frac{\partial f}{\partial x_1} dx_1 \wedge dx_2 + \frac{\partial g}{\partial x_2} dx_1 \wedge dx_2$$

$$= \left(\frac{\partial f}{\partial x_1} + \frac{\partial g}{\partial x_2}\right) dx_1 \wedge dx_2$$

So it is enough to show that $\frac{\partial f}{\partial x_1} = -\frac{\partial g}{\partial x_2}$ *

$$\frac{\partial f}{\partial x_1} = \frac{x_1^2 + x_2^2 - 2x_1^2}{(x_1^2 + x_2^2)^2} = \frac{x_2^2 - x_1^2}{(x_1^2 + x_2^2)^2}$$

$$\frac{\partial g}{\partial x_2} = \frac{x_1^2 + x_2^2 - 2x_2^2}{(x_1^2 + x_2^2)^2} = -\frac{x_2^2 - x_1^2}{(x_1^2 + x_2^2)^2}$$

So * is true and

$$d\Omega_1 = 0$$

Next that $d\Omega_2 = 0$

$$\Omega_2 = |x|^{-3} (x_1 dx_2 \wedge dx_3 - x_2 dx_1 \wedge dx_3 + x_3 dx_1 \wedge dx_2)$$

$$= \frac{x_1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_2 \wedge dx_3 - \frac{x_2}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_1 \wedge dx_3 + \frac{x_3}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_1 \wedge dx_2$$

Using the same argument as previously, $d\Omega_2 = 0$ iff

$$\begin{aligned} (*) \quad \frac{\partial}{\partial x_1} \underbrace{\left(\frac{x_1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right)}_{f(x_1, x_2, x_3)} + \frac{\partial}{\partial x_2} \underbrace{\left(\frac{x_2}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right)}_{g(x_1, x_2, x_3)} + \frac{\partial}{\partial x_3} \underbrace{\left(\frac{x_3}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right)}_{h(x_1, x_2, x_3)} &= 0 \\ \frac{\partial f}{\partial x_1} = \frac{-2x_1^2 + x_2^2 + x_3^2}{(x_1^2 + x_2^2 + x_3^2)^{5/2}} & \quad \frac{\partial g}{\partial x_2} = \frac{-2x_2^2 + x_1^2 + x_3^2}{(x_1^2 + x_2^2 + x_3^2)^{5/2}} & \quad \frac{\partial h}{\partial x_3} = \frac{-2x_3^2 + x_1^2 + x_2^2}{(x_1^2 + x_2^2 + x_3^2)^{5/2}} \end{aligned}$$

so $(*)$ is true and $d\Omega_2 = 0$

General statement: $\Omega_{n-1} = |x|^{-n} \left(\sum_{i=1}^n (-1)^{i+1} x_i dx_{1-i} \right)$

PF:

$$\Rightarrow d\Omega_{n-1} = 0$$

uses notation from lecture

Let Ω_{n-1} be a $(n-1)$ -form as described above

Then we rewrite

$$\Omega_{n-1} = \sum_{i=1}^n \left(\frac{(-1)^{i+1} x_i}{\left(\sum_{j=1}^n x_j^2 \right)^{n/2}} dx_{1-i} \right)$$

Then

$$d\Omega_{n-1} = \sum_{i=1}^n (-1)^{i+1} d \left(\frac{x_i}{\left(\sum_{j=1}^n x_j^2 \right)^{n/2}} \right) \wedge dx_{1-i}$$

$$\ast = \sum_{i=1}^n (-1)^{i+1} \frac{\partial}{\partial x_i} \left(\frac{x_i}{\left(\sum_{j=1}^n x_j^2\right)^{n/2}} \right) dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_n$$

The dx_i is moved into the wedges $i-1$ times so they all line up, necessitating all terms $i-1$ times.

since $\frac{\partial}{\partial x_i} \left(\left(\sum_{j=1}^n x_j^2\right)^{n/2} \right) = n x_i \left(\sum_{j=1}^n x_j^2\right)^{n/2-1}$

$$\ast = \sum_{i=1}^n \frac{\left(\sum_{j=1}^n x_j^2\right)^{n/2} - n x_i^2 \left(\sum_{j=1}^n x_j^2\right)^{n/2-1}}{\left(\sum_{j=1}^n x_j^2\right)^n} dx_1 \wedge \dots \wedge dx_n$$

$$= \sum_{i=1}^n \frac{\left(\sum_{j=1}^n x_j^2\right)^{n/2-1} \left(\sum_{j=1}^n x_j^2 - n x_i^2\right)}{\left(\sum_{j=1}^n x_j^2\right)^n}$$

$$= \frac{1}{\left(\sum_{j=1}^n x_j^2\right)^{n/2+1}} \underbrace{\left(n \left(\sum_{j=1}^n x_j^2\right) - n \left(\sum_{i=1}^n x_i^2\right) \right)}_{=0}$$

$$= 0$$

so $d\Omega_{n-2} = 0$

let $\gamma: [0, 1]^2 \rightarrow \mathbb{R}^3$ be a 2-cell on \mathbb{R}^3 defined by

$$\gamma: (s, t) \mapsto \begin{pmatrix} \sin(\pi s) \cos(2\pi t) \\ \sin(\pi s) \sin(2\pi t) \\ \cos(\pi s) \end{pmatrix}$$

what is $\int_Y \Omega_2$? Recall

$$\Omega_2 = |x|^{-3} (x_1 dx_2 \wedge dx_3 - x_2 dx_1 \wedge dx_3 + x_3 dx_1 \wedge dx_2)$$

$$= \frac{x_1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_2 \wedge dx_3 - \frac{x_2}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_1 \wedge dx_3$$

$$+ \frac{x_3}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} dx_1 \wedge dx_2$$

since γ output coordinate to unit sphere, $|x| = 1$

$$\int_{\gamma} \Omega_2 = \int_{\gamma} x_1 dx_2 \wedge dx_3 - x_2 dx_1 \wedge dx_3 + x_3 dx_1 \wedge dx_2$$

$$= \int_0^1 \int_{s=0}^1 \left(\sin(\pi s) \cos(2\pi t) \det \begin{bmatrix} \frac{\partial x_2}{\partial s} & \frac{\partial x_2}{\partial t} \\ \frac{\partial x_3}{\partial s} & \frac{\partial x_3}{\partial t} \end{bmatrix} \right.$$

$$\left. - \sin(\pi s) \sin(2\pi t) \det \begin{bmatrix} \frac{\partial x_1}{\partial s} & \frac{\partial x_1}{\partial t} \\ \frac{\partial x_3}{\partial s} & \frac{\partial x_3}{\partial t} \end{bmatrix} \right.$$

$$\left. + \cos(\pi s) \det \begin{bmatrix} \frac{\partial x_1}{\partial s} & \frac{\partial x_1}{\partial t} \\ \frac{\partial x_2}{\partial s} & \frac{\partial x_2}{\partial t} \end{bmatrix} \right) ds dt$$

Now since

$$\frac{\partial x_1}{\partial s} = \pi \cos(\pi s) \cos(2\pi t), \quad \frac{\partial x_1}{\partial t} = -2\pi \sin(\pi s) \sin(2\pi t)$$

$$\frac{\partial x_2}{\partial s} = \pi \cos(\pi s) \sin(2\pi t), \quad \frac{\partial x_2}{\partial t} = 2\pi \sin(\pi s) \cos(2\pi t)$$

$$\frac{\partial x_3}{\partial s} = -\pi \sin(\pi s), \quad \frac{\partial x_3}{\partial t} = 0$$

$$\det \begin{bmatrix} \frac{\partial x_2}{\partial s} & \frac{\partial x_2}{\partial t} \\ \frac{\partial x_3}{\partial s} & \frac{\partial x_3}{\partial t} \end{bmatrix} = \pi \cos(\pi s) \cos(2\pi t) \cdot 0 - 2\pi^2 \sin(\pi s)^2 \cos(2\pi t)$$

$$\det \begin{bmatrix} \frac{\partial x_1}{\partial s} & \frac{\partial x_1}{\partial t} \\ \frac{\partial x_3}{\partial s} & \frac{\partial x_3}{\partial t} \end{bmatrix} = 2\pi^2 \sin(\pi s)^2 \sin(2\pi t)$$

$$\det \begin{bmatrix} \frac{\partial x_1}{\partial s} & \frac{\partial x_1}{\partial t} \\ \frac{\partial x_2}{\partial s} & \frac{\partial x_2}{\partial t} \end{bmatrix} = 2\pi^2 \sin(\pi s) \cos(\pi s) \sin(2\pi t) \cos(2\pi t) \\ + 2\pi^2 \cos(\pi s) \sin(\pi s) \sin(2\pi t)^2$$

$$\int_0^1 \Omega_2 = \int_{t=0}^1 \int_{s=0}^1 \left(\sin(\pi s) \cos(2\pi t) (-2\pi^2 \sin(\pi s)^2 \cos(2\pi t)) \right. \\ \left. - \sin(\pi s) \sin(2\pi t) (2\pi^2 \sin(\pi s)^2 \sin(2\pi t)) \right. \\ \left. + \cos(\pi s) (2\pi^2 \sin(\pi s) \cos(\pi s) \sin(2\pi t) \cos(2\pi t)) \right. \\ \left. + 2\pi^2 \cos(\pi s) \sin(\pi s) \sin(2\pi t)^2 \right) ds dt$$

$$= \int_{t=0}^1 \int_{s=0}^1 2\pi^2 \sin(\pi s)^3 + 2\pi^2 \cos(\pi s)^3 \sin(\pi s) ds dt$$

↳ Got stuck here, luckily

$$\stackrel{x}{=} 2\pi^2 \int_{t=0}^1 \int_{s=0}^1 \sin \pi s ds dt$$

Jianzhi

$$= 2\pi^2 \int_{t=0}^1 \left[-\frac{\cos(\pi s)}{\pi} \right]_0^1 dt$$

found away to simplify this.

$$= 2\pi^2 \int_{t=0}^1 \frac{1}{\pi} (1+1) dt$$

this.

$$= 2\pi^2 \int_{t=0}^1 \frac{2}{\pi} dt = 4\pi$$

Good job

$$\star \cos^2(x) + \sin^2(x) = 1$$

I have not been able to show this myself.

My thoughts on this were, assuming the statement is

true, that somehow we could transform this into

polar coordinates using \sin , \cos , I have not had any

success though, sadly. All out of luck, I read Jianzhi's

solution, which was a great way of using the same

method as before to reduce the term to

$\int \frac{4}{(1+r^2+t^2)^2} da db$ and reducing to polar coordinates,
set $bt = r$ 4π .