

Math 105 HW 10

Reading

(12) a) Let  $\vec{p} = (p_1, p_2, p_3) \in \mathbb{R}^3$ . We have that

$$\begin{aligned}(\nabla f_i)(f^{-1}(\vec{p})) &= \nabla f_i(x, y) \\ &= (f_{i_x}(x, y), f_{i_y}(x, y)) \\ &= (-a \sin(x) \cos(y), -(b + a \cos(x)) \sin(y))\end{aligned}$$

where  $f(x, y) = \vec{p}$ . To have  $(\nabla f_i)(f^{-1}(\vec{p})) = 0$  we must thus have

$$\begin{aligned}\textcircled{1} \quad \sin(x) &= 0 & \text{or} \quad \cos(y) &= 0 \\ \textcircled{2} \quad \sin(y) &= 0 & \text{or} \quad \cos(x) &= -\frac{b}{a}\end{aligned}$$

Case 1:  $\sin(x) = 0$

Then,  $x = k\pi$  for some  $k \in \mathbb{Z}$ . This means  $\cos(x) = \pm 1$ . But since  $a < b$ ,

$\cos(x) \neq -\frac{b}{a}$ , so we must have  $\sin(y) = 0$ , or  $y = m\pi$  for some  $m \in \mathbb{Z}$ .

Case 2:  $\cos(y) = 0$

Then,  $y = k\pi + \frac{\pi}{2}$  for some  $k \in \mathbb{Z}$ . This means  $\sin(y) \neq 0$ , so we must have

$\cos(x) = -\frac{b}{a} \Rightarrow$  not possible since  $0 < a < b$ .

Now, we compute the possible values of  $\vec{p}$ .

For Case 1:

$k, m \in \mathbb{Z}$  even  $\Rightarrow (b + a \cos(x), 0, 0)$

$$f(x, y) = (a + b, 0, 0)$$

$k$  even,  $m$  odd:

$$f(x, y) = (-a - b, 0, 0)$$

$k$  odd,  $m$  even:

$$f(x, y) = (-a + b, 0, 0)$$

$k, m$  odd:

$$f(x, y) = (a - b, 0, 0)$$

So there are exactly 4 points.

b) We have

$$\nabla f_3(x, y) = (a \cos(x), 0)$$

For this to equal 0 we want  
 $\cos(x) = 0 \Leftrightarrow x = \frac{\pi}{2} + k\pi$  for  $k \in \mathbb{Z}$ .

$f(\frac{\pi}{2} + k\pi, y)$  is

$$\begin{cases} (b \cos(y), b \sin(y), a) & k \text{ even} \\ (b \cos(y), b \sin(y), -a) & k \text{ odd} \end{cases}$$

So this describes the possible values for  $\vec{z}$ .

$$c) f_{11s}(s, t) = -a \cos(s) \cos(t)$$

$$f_{11t}(s, t) = a \sin(s) \sin(t)$$

$$f_{11ts}(s, t) = a \sin(s) \sin(t)$$

$$f_{11tt}(s, t) = -(b + a \cos(s)) \cos(t)$$

For the second derivative test,

$$D = f_{11ss} f_{11tt} - (f_{11st})^2$$

$$= ab \cos(s) \cos(t)^2 + a^2 \cos(s)^2 \cos(t)^2 - a^2 \sin(s)^2 \sin(t)^2$$

For our four cases:

①  $k, m$  even

$$D = ab + a^2 > 0$$

$$f_{11ss} = -a < 0$$

↳ local max

②  $k$  even,  $m$  odd

$$D = ab + a^2 > 0$$

$$f_{11ss} = a > 0$$

↳ local min

③  $k$  odd,  $m$  even

$$D = -ab + a^2 < 0$$

↳ saddle point

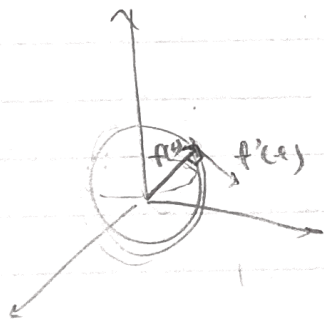
④  $k, m$  odd

$$D = -ab + a^2 < 0$$

↳ saddle point

(13) Suppose  $\vec{f}(t) = (f_1(t), f_2(t), f_3(t))$ :  
 $|\vec{f}(t)| = 1$  means  $f_1(t)^2 + f_2(t)^2 + f_3(t)^2 = 1$   
 So taking the derivative wrt  $t$ ,  
 $2f_1(t) \cdot f_1'(t) + 2f_2(t) \cdot f_2'(t) + 2f_3(t) \cdot f_3'(t) = 0$ .  
 Dividing by 2 yields  $\vec{f}'(t) \cdot \vec{f}(t) = 0$   
 as desired.

Geometric interpretation: The image of  $f$  is on the unit sphere, where the vector  $\vec{f}(t)$  will always be orthogonal to the gradient.



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$$\begin{aligned} \textcircled{1} \quad & 3x + y - z + u^2 = 0 \\ \textcircled{2} \quad & x - y + 2z + u = 0 \\ \textcircled{3} \quad & 2x + 2y - 3z + 2u = 0 \end{aligned}$$

$x, y, u$  in terms of  $z$ :

$$\textcircled{1} + \textcircled{2} \Rightarrow$$

$$4x + z + u^2 + u = 0$$

$$2 \cdot \textcircled{2} + \textcircled{3} \Rightarrow$$

$$4x + z + 4u = 0$$

$$u^2 - 3u = 0, \quad u = 0 \text{ or } 3$$

$$x = \frac{-4u - z}{4}$$

$$y = u^2 + z - 3x$$

Solutions:

$$\begin{cases} u = 0 \\ x = -\frac{z}{4} \\ y = \frac{7}{4}z \end{cases}$$

or

$$\begin{cases} u = 3 \\ x = -3 - \frac{z}{4} \\ y = 18 + \frac{7}{4}z \end{cases}$$

$x, z, u$  in terms of  $y$ :

• same operations give  $u = 0$  or  $3$

$$2 \cdot \textcircled{1} + \textcircled{2} \Rightarrow$$

$$7x + y + 2u^2 + u = 0$$

$$x = \frac{-y - 2u^2 - u}{7}$$

$$z = 3x + y + u^2$$



Solutions:

$$\begin{cases} u = 0 \\ x = \frac{-y}{7} \\ z = \frac{4y}{7} \end{cases}$$

$$\begin{cases} u = 3 \\ x = \frac{-y-21}{7} \\ z = \frac{4y}{7} \end{cases}$$

$y, z, u$  in terms of  $x$ :

•  $u = 0$  or  $3$

• from previous work,

$$z = -4x - 4u$$

$$y = x + 2z + 4u$$

Solutions:

$$\begin{cases} u = 0 \\ z = -4x \\ y = -7x \end{cases}$$

$$\begin{cases} u = 3 \\ z = -4x - 12 \\ y = -7x - 24 \end{cases}$$

$x, y, z$  in terms of  $u$ :

The system is

$$\begin{bmatrix} 3 & 1 & -1 \\ 1 & -1 & 2 \\ 2 & 2 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -u^2 \\ -u \\ -2u \end{bmatrix}$$

Since the first row is the sum of the other 2 but  $-3u \neq -u^2$  necessarily

there is no solution.

Pugh

(14) a) Not open.

Consider  $A_\epsilon = \begin{bmatrix} 1 & \epsilon \\ 0 & 1 \end{bmatrix}$ . ( $\epsilon > 0$ ). To find the eigenvalues we need to solve  $\det(A - \lambda I) = 0$ , or

$$\det \begin{bmatrix} 1-\lambda & \epsilon \\ 0 & 1-\lambda \end{bmatrix} = 0$$

$$(1-\lambda)^2 = 0$$

$$\lambda = 1$$

Note that

$$\begin{bmatrix} 1 & \epsilon \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + \epsilon x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

implies  $x_2 = 0$ , so the dimension of the eigenspace is 1. This implies that  $A_\epsilon$  is not diagonalizable.

Thus since  $I$  is diagonalizable and  $\epsilon$  is arbitrary we can get arbitrarily close to  $I$  with non-diagonalizable matrices, so the set of diagonalizable matrices is not open in  $M(n \times n)$ .

b) Not closed

A closed set contains all limit points.

Note that from a) the matrix

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

is not diagonalizable. Consider

$$A_\epsilon = \begin{bmatrix} 1 & 1 \\ \epsilon^2 & 1 \end{bmatrix}$$

for  $0 < \epsilon < 1$ . Solving for the eigenvalues:

$$\det \begin{bmatrix} 1-\lambda & 1 \\ \epsilon^2 & 1-\lambda \end{bmatrix} = 0$$

$$(1-\lambda)^2 - \epsilon^2 = 0$$

$$1-\lambda = \pm \epsilon$$

$$\lambda = -1 \pm \epsilon$$

Since there are two distinct eigenvalues, we can write a basis of eigenvectors that spans  $\mathbb{R}^2$ , so  $A_\epsilon$  is diagonalizable.

Taking  $\epsilon \rightarrow 0$  we approach  $A$ , but

$A$  is not diagonalizable. Therefore

the set is not closed.



c) Not dense

A set  $X \subseteq Y$  is dense if  $\forall y \in Y, \epsilon > 0$   
 $\exists x \in X$  s.t.  $d(x, y) < \epsilon$ .

Consider  $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ ,  $B = \begin{bmatrix} \epsilon_1 & \epsilon_2 - 1 \\ \epsilon_3 + 1 & \epsilon_4 \end{bmatrix}$

Note that

$$\det \begin{bmatrix} \epsilon_1 - \lambda & \epsilon_2 - 1 \\ \epsilon_3 + 1 & \epsilon_4 - \lambda \end{bmatrix} = 0$$

$\Leftrightarrow$

$$(\epsilon_1 - \lambda)(\epsilon_4 - \lambda) - (\epsilon_2 - 1)(\epsilon_3 + 1) = 0$$

$\Leftrightarrow$

$$\lambda^2 - (\epsilon_1 + \epsilon_4)\lambda + \epsilon_1\epsilon_4 - \epsilon_2\epsilon_3 - \epsilon_2 + \epsilon_3 + 1 = 0$$

The discriminant of this quadratic is

$$\begin{aligned} & (\epsilon_1 + \epsilon_4)^2 - 4[\epsilon_1\epsilon_4 - \epsilon_2\epsilon_3 - \epsilon_2 + \epsilon_3 + 1] = \\ & [(\epsilon_1 + \epsilon_4)^2 - 4\epsilon_1\epsilon_4 + 4\epsilon_2\epsilon_3 + 4\epsilon_2 - 4\epsilon_3] - 4 \end{aligned}$$

As  $\epsilon_1, \epsilon_2, \epsilon_3, \epsilon_4 \rightarrow 0$ , this approaches  $-4$ ,  
so the quadratic has no solutions and thus  $B$   
has no eigenvalues and is not diagonalizable.

Therefore for sufficiently small  $\epsilon$ ,  
 $B(A, \epsilon) \subseteq \{ \text{not diagonalizable } 2 \times 2 \text{ matrices} \}$

So the set of diagonalizable matrices  
must not be dense.

(24) clearly all partials exist at points other than the origin, since  $f$  is a quotient of smooth functions and the denominator is non-zero. Thus we focus our attention to  $(0,0)$ . We have

$$\frac{\partial f(0,0)}{\partial x} = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{0 - 0}{h}$$

$$= 0$$

$$\frac{\partial f(0,0)}{\partial y} = \lim_{h \rightarrow 0} \frac{f(0,h) - f(0,0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{0 - 0}{h}$$

$$= 0$$

(for  $(x,y) \neq (0,0)$ )

$$\frac{\partial f}{\partial x} = \frac{y(x^2 - y^2) + 2x^2y}{x^2 + y^2} - \frac{2(x^2 - y^2)}{(x^2 + y^2)^2}$$

$$\frac{\partial f}{\partial y} = \frac{x(x^2 - y^2) - 2xy^2}{x^2 + y^2} - \frac{2x(x^2 - y^2)}{(x^2 + y^2)^2}$$

$$\begin{aligned} \frac{\partial^2 f(0,0)}{\partial x^2} &= \lim_{h \rightarrow 0} \frac{\frac{\partial f}{\partial x}(h,0) - \frac{\partial f}{\partial x}(0,0)}{h} \\ &= \lim_{h \rightarrow 0} \frac{0 - 0}{h} \\ &= 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 f(0,0)}{\partial y^2} &= \lim_{h \rightarrow 0} \frac{\frac{\partial f}{\partial y}(0,h) - \frac{\partial f}{\partial y}(0,0)}{h} \\ &= \lim_{h \rightarrow 0} \frac{0 - 0}{h} \\ &= 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 f(0,0)}{\partial x \partial y} &= \lim_{h \rightarrow 0} \frac{\frac{\partial f}{\partial x}(0,h) - \frac{\partial f}{\partial x}(0,0)}{h} \\ &= \lim_{h \rightarrow 0} \left( \frac{-h^3}{h^2} + \frac{h^3}{2h^4} \right) \frac{1}{h} \\ &= \lim_{h \rightarrow 0} -1 + \frac{1}{2h^2} \\ &= -1 \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 f(0,0)}{\partial y \partial x} &= \lim_{h \rightarrow 0} \frac{\frac{\partial f}{\partial y}(h,0) - \frac{\partial f}{\partial y}(0,0)}{h} \\ &= \lim_{h \rightarrow 0} \left( \frac{h^3}{h^2} - \frac{h^3}{2h^4} \right) \frac{1}{h} \\ &= \lim_{h \rightarrow 0} 1 - \frac{1}{2h^2} = 1 \end{aligned}$$