

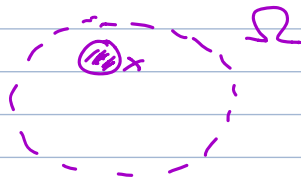
1. Open sets and Closed sets:

• $X = \mathbb{C}$

• basic open set: $D_\varepsilon(x) = \{y \in \mathbb{C} \mid |y-x| < \varepsilon\}$.

• $\Omega \subset \mathbb{C}$: Ω is open, if $\forall x \in \Omega$, $\exists D_\varepsilon(x)$, such $x \in D_\varepsilon(x) \subset \Omega$

• $A \subset \mathbb{C}$; A is closed if $A^c = \mathbb{C} \setminus A$ is open.



basic properties: • $\bigcup_\alpha U_\alpha$ is open if each U_α is open.

$\{ |y-x| \leq \frac{1}{n} \}$ • $\bigcap_\alpha A_\alpha$ is closed, if A_α is closed.

Ex: $\bigcap_{n=1}^{\infty} \overline{D_{\frac{1}{n}}(x)} = \{x\}$.

open: $\bigcup_{n=1}^{\infty} (n-1, n+1) \times (-\frac{1}{n}, \frac{1}{n})$



• Let $Z \subset \mathbb{C}$

• interior point: $z \in Z$ is an interior point, if $\exists U$ open nbhd of z , s.t. $U \subset Z$. [or. $\exists D_\varepsilon(z) \subset Z$]

• $\text{int}(Z)$: set of all interior points.

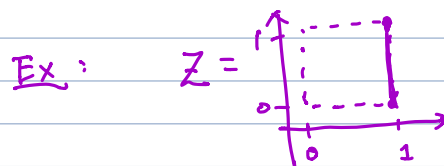
• limit point: $z_0 \in \mathbb{C}$ is a limit point of Z , if there exist a seq of points in Z , z_1, z_2, z_3, \dots , such that $\lim_{i \rightarrow \infty} z_i = z_0$ (i.e. $\forall \varepsilon > 0$, $\exists N$ big enough, such. $\forall n > N$, $|z_n - z_0| < \varepsilon$.)

• \overline{Z} = the set of limit points of Z .

" = smallest closed set containing Z ."

= $\bigcap_{\substack{A \text{ closed} \\ A \supset Z}} A$

(called the closure of Z)



• $\partial Z = \overline{Z} \setminus \text{int}(Z)$.

$\partial Z =$ (all 4 edges)

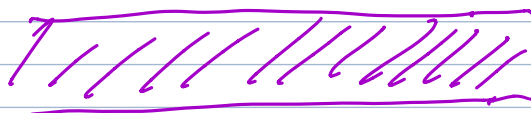
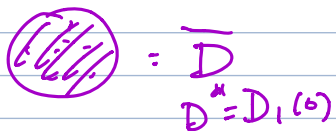
• compact sets :

• bounded set: it can be covered by $D_R(0)$ for R large enough.

(less general) • $K \subset \mathbb{C}$ is a compact subset, if it is closed and bounded.

unit closed disk.

Ex:



$\mathbb{R} \times [0, 1]$.

closed but not bounded.

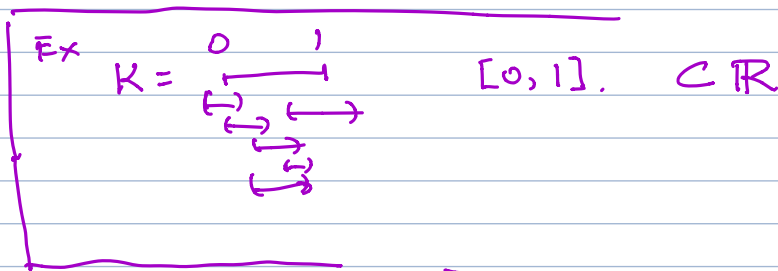
\Rightarrow not compact.

Equivalently:

(1) • sequential compactness: K is seq. compact, if for any sequence in K , z_1, z_2, \dots , there is a subsequence $z_{i_1}, z_{i_2}, z_{i_3}, \dots$ such that $\lim_{k \rightarrow \infty} z_{i_k}$ exists and is in K . $i_1 < i_2 < i_3 \dots$

(2) • (finite open cover.): K is compact, if for any open covering of K , i.e. $\{U_\alpha \text{ open, } \alpha \in I\}$, $K \subset \bigcup_{\alpha \in I} U_\alpha$ then, there exists a finite subset $I_0 \subset I$, such that

$$K \subset \bigcup_{\alpha \in I_0} U_\alpha$$



• Continuous Function:

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

source \swarrow target \nwarrow

Def: $f: \mathbb{R} \rightarrow \mathbb{R}$ be a function, it is

continuous if $\forall x \in \mathbb{R}, \forall \varepsilon > 0, \exists \delta > 0$

$$\text{s.t. } \forall x' \in \mathbb{R} \quad |x' - x| < \delta$$

$$\Rightarrow |f(x') - f(x)| < \varepsilon.$$

can be generalized to

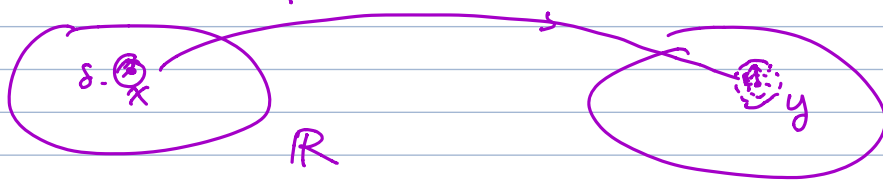
$$\mathbb{R}^n \rightarrow \mathbb{R}^m,$$

$$\mathbb{C} \rightarrow \mathbb{C}.$$

$$\Omega \rightarrow \mathbb{R}.$$

$$\Omega \rightarrow \mathbb{C}$$

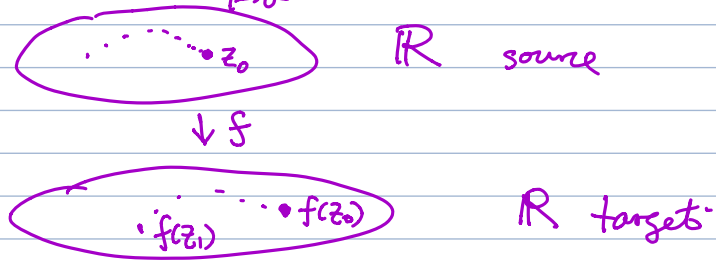
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Equivalent definition for f being continuous: (1) for all open set $V \subset \mathbb{R}^{\text{target}}$, $f^{-1}(V)$ is open. (only need open set)
 "preimage of open is open"

(2) "f preserves limit".

say $z_1, \dots, z_n, \dots \in \mathbb{R}^{\text{source}}$, s.t. $\lim_{i \rightarrow \infty} z_i = z_0$.
 then $f(z_0) = \lim_{i \rightarrow \infty} f(z_i)$.



Property: If f is a continuous function, K is compact (in the source), then $f(K)$ is compact.

\downarrow continuous.
 $C^0, C^1, C^2, \dots, C^k, \dots$
 C^∞ (smooth function)

C^ω : real analytic.

Holomorphic Function:

let $f: \Omega \rightarrow \mathbb{C}$, ($\Omega \subset \mathbb{C}$ open)
 we say f is hol'c at $z_0 \in \Omega$, if the following limit exist.

$$\frac{f(z_0+h) - f(z_0)}{h} \leftarrow \text{as } h \rightarrow 0, h \in \mathbb{C}$$

(if it exist, call it $f'(z_0)$).

f is hol'c in Ω if f is hol'c at every point in Ω .

Ex: (1) $f: \mathbb{C} \rightarrow \mathbb{C}$, $f(z) = z^n$, (n integer, > 0).

$$f(z+h) - f(z) = (z+h)^n - z^n = z^n + n \cdot h \cdot z^{n-1} + O(h^2) - z^n$$

$$= n \cdot h \cdot z^{n-1} + o(h^2)$$

$$\lim_{h \rightarrow 0} \frac{n h \cdot z^{n-1} + o(h^2)}{h} = \lim_{h \rightarrow 0} n \cdot z^{n-1} + o(h) = n \cdot z^{n-1}$$

$$(2). \quad f: \mathbb{C} \rightarrow \mathbb{C}, \quad f(z) = \bar{z},$$

$$\frac{f(z+h) - f(z)}{h} = \frac{\overline{z+h} - \bar{z}}{h} = \frac{\bar{z} + \bar{h} - \bar{z}}{h}$$

$$= \frac{\bar{h}}{h}$$

write $h = \varepsilon \cdot e^{i\theta}$, then $\bar{h} = \varepsilon \cdot e^{-i\theta}$

$$\frac{\bar{h}}{h} = \frac{\varepsilon \cdot e^{-i\theta}}{\varepsilon \cdot e^{i\theta}} = e^{-2i\theta}$$

\Rightarrow $\lim(\dots)$ of $h \rightarrow 0$ does not exist.

(3). $\frac{1}{z}$ is hol'c on $\mathbb{C} \setminus \{0\}$.

\bar{z}^n is not hol'c.

$z \cdot \bar{z}$ is not hol'c.

• View $f: \mathbb{C} \rightarrow \mathbb{C}$ as $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$. $(x,y) \mapsto (u,v)$
 $\mathbb{C} \cong \mathbb{R}^2$ $z = x+iy$. $z \leftrightarrow (x,y)$.

• Suppose F is C^1 , differentiable. i.e.

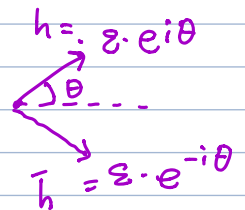
$\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}$ exists and continuous.

Tex.: $f = \bar{z}$, $(x,y) \mapsto (x,-y)$
 $P \in \mathbb{R}^2, H \in \mathbb{R}^2$

$$\frac{F(P+H) - F(P)}{H}$$

cannot (in general), divide a vector by a vector.

\Uparrow F is real differentiable as $\mathbb{R}^2 \rightarrow \mathbb{R}^2$



$$F(P+H) = F(P) + \underbrace{I}_{2 \times 2 \text{ matrix}} \cdot H + H \cdot \underbrace{\Psi(H)}_{\rightarrow 0 \text{ as } |H| \rightarrow 0}$$

$$I = \begin{pmatrix} \frac{\partial u'}{\partial x} & \frac{\partial v'}{\partial x} \\ \frac{\partial u'}{\partial y} & \frac{\partial v'}{\partial y} \end{pmatrix} = dF|_P$$

• Now, let's use the fact f is hol'c. $P = (x, y)$
 let $h = h_1 + i h_2$. $z = x + iy$.

• h is real: $h = h_1$ $f(z) = u + iv$.

$$\frac{f(z+h) - f(z)}{h} = \frac{u(x+h_1, y) + i v(x+h_1, y) - (u(x, y) + i v(x, y))}{h_1}$$

$$= \frac{u(x+h_1, y) - u(x, y)}{h_1} + i \frac{v(x+h_1, y) - v(x, y)}{h_1}$$

$$\xrightarrow{h_1 \rightarrow 0} \frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = f'(z)$$

• h is purely imaginary, $h = i h_2$.

$$\frac{u(x, y+h_2) - u(x, y)}{i h_2} + i \frac{v(x, y+h_2) - v(x, y)}{i h_2}$$

$$\xrightarrow{h_2 \rightarrow 0} \frac{1}{i} \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y} = f'(z)$$

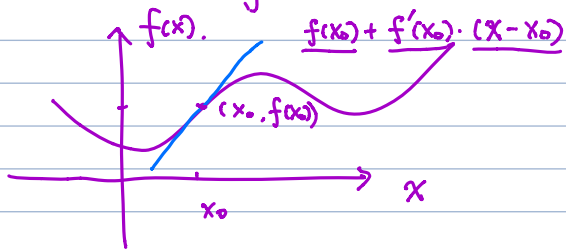
$$\begin{cases} \text{Cauchy} \\ \text{Riemann} \end{cases} \Rightarrow \begin{cases} \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \\ \frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} \end{cases} \iff f \text{ being hol'c at point } z.$$

evaluated at point z .

$ex: f(x, y) = \sqrt{|x| \cdot |y|}$
 at point 0.

$(u, v$ being differentiable.
 $+ u, v$ satisfies CR. $\implies f$ is hol'c. Thm 2.4

• real 1-dim. $f: \mathbb{R} \rightarrow \mathbb{R}$



$$f(x) = f(x_0) + f'(x_0)(x - x_0) + o(|x - x_0|)$$

complex 1-dim: f is hol'c at z_0 . $\frac{\text{a term}}{|x - x_0|} \rightarrow 0$ as $x \rightarrow x_0$.

$$f(z) = f(z_0) + f'(z_0)(z - z_0) + o(|z - z_0|).$$