

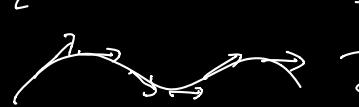
Today: (1). First, Second variation formula.

(2). Jacobi equation (for family of geodesics).

(M, g) . $S \subset M$ submfld.

$TM|_S = \{(x, \xi) \in TM \mid x \in S, \xi \in T_x M\}$.

$\Gamma(S, TM|_S)$:  picture for Y .

$\Gamma(S, TS)$:  picture for X

∇^M, ∇^S .

let $x \in \Gamma(S, TS), Y \in \Gamma(S, TM|_S)$

How to define $\nabla_x^M Y$?

method ① : extend x, Y to

U nbhd of S


$$\tilde{x} \in \Gamma(U, TM) \quad \tilde{x}|_S = x$$

$$\tilde{Y} \in \Gamma(U, TM), \quad \tilde{Y}|_S = Y.$$

$$\nabla_x^M Y := (\nabla_{\tilde{x}}^M \tilde{Y})|_S \in \Gamma(S, TM|_S)$$

Γ doesn't ~~dep~~ dep on extension.

say \tilde{x}_1, \tilde{x}_2 both extends x ,

$$(\tilde{x}_1 - \tilde{x}_2)|_S = 0.$$

$$\left(\nabla_{(\tilde{x}_1 - \tilde{x}_2)}^M (\tilde{Y}) \right)|_S^{ij} = \underbrace{(\tilde{x}_1 - \tilde{x}_2)^i}_{=0} \left[\partial_i (\tilde{Y}^j) + \Gamma_{ik}^j \cdot \tilde{Y}^k \right] |_S$$

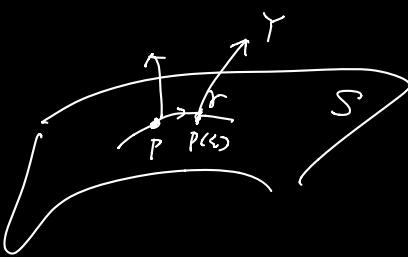
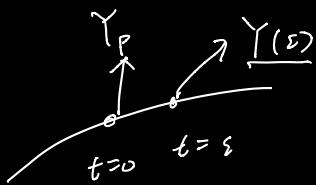
similarly, if \tilde{Y}_1, \tilde{Y}_2 both extends Y ,

$$\left(\nabla_{\tilde{x}}^M (\tilde{Y}_2 - \tilde{Y}_1) \right)|_S = 0.$$

method ② : use parallel transport.

$$\cdot (\nabla \times Y)|_P = \lim_{\varepsilon \rightarrow 0} \frac{P_{P(\varepsilon) \rightarrow P}(Y_{P(\varepsilon)}) - Y_P}{\varepsilon}$$

$$P(t) = \Phi^X_t(p).$$



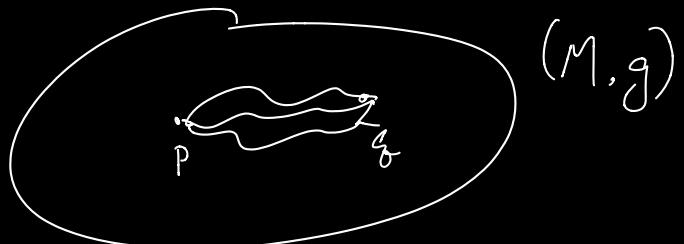
Given X on S

we use that to generate little path, do parallel transport along those path.

Variation Formula:

$$E = \frac{1}{2} \int_0^1 |\dot{\gamma}(t)|_g^2 dt.$$

(for simplicity, assume γ s are smooth path).



$\Sigma_{p,q}$: path

1st variation:

1-param family $\alpha_s(t)$, $s \in (-\varepsilon, \varepsilon)$

$$\frac{d}{ds} E(\alpha_s) = \frac{1}{2} \int_0^1 \frac{\partial}{\partial s} \langle \partial_t \alpha, \partial_t \alpha \rangle dt$$

$$= \int_0^1 \langle \nabla_{\partial_s} \partial_t \alpha, \partial_t \alpha \rangle dt.$$

symmetry Lemma

$$= \int_0^1 \langle \nabla_{\partial_t} \partial_s \alpha, \partial_t \alpha \rangle dt$$

I.B.P.

$$= \int_0^1 - \langle \partial_s \alpha, \nabla_{\partial_t} \partial_t \alpha \rangle dt + \left. \langle \partial_s \alpha, \partial_t \alpha \rangle \right|_{t=0}$$

set $s=0$.

$$E_*(\delta \alpha) = \int_0^1 - \langle \delta \alpha, \nabla_{\partial_t} \partial_t \alpha \rangle dt.$$

$$\delta \alpha = \left. \frac{d}{ds} \right|_{s=0} \alpha.$$

2nd Variation Formula:

• γ is a geodesic $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$.

• $\alpha_{s_1, s_2}(t)$. $s_i \in (-\varepsilon, \varepsilon)$.

$$\alpha_{0,0}(t) = \gamma(t)$$

• $\overbrace{\frac{\partial^2}{\partial s_1 \partial s_2}} E(\alpha_{s_1, s_2})$.

$$= \frac{\partial}{\partial s_1} \left(\frac{1}{2} \int_0^1 \frac{\partial}{\partial s_2} \langle \partial_t \alpha, \partial_t \alpha \rangle dt \right)$$

$$= \frac{\partial}{\partial s_1} \left(- \int_0^1 \left\langle \frac{\partial}{\partial s_2} \alpha, \nabla_{\partial_t} \partial_t \alpha \right\rangle dt \right)$$

$\because (s_1, s_2)$ are free.

$$= - \int_0^1 \left\{ \left\langle \nabla_{\partial_{s_1}} \frac{\partial \alpha}{\partial s_2}, \nabla_{\partial_t} \partial_t \alpha \right\rangle \right.$$

$$S = (-\varepsilon, \varepsilon) \times (-\varepsilon, \varepsilon) \times [t_0, t_1]$$

$$\alpha: S \rightarrow M.$$

$$\left. + \left\langle \frac{\partial}{\partial s_2} \alpha, \nabla_{\partial_{s_1}} \nabla_{\partial_t} \partial_t \alpha \right\rangle \right\} dt$$

now, setting $(s_1, s_2) = (0, 0)$, then $\nabla_{\partial_t} \partial_t \alpha = 0$.

$$\Rightarrow = - \int_0^1 \left\langle \partial_{s_2} \alpha, \nabla_{\partial_{s_1}} \nabla_{\partial_t} \partial_t \alpha \right\rangle dt$$

$$\left. \begin{aligned} & \nabla_{\partial_{s_1}} \nabla_{\partial_t} - \nabla_{\partial_t} \nabla_{\partial_{s_1}} - \nabla_{[\partial_{s_1}, \partial_t]} \end{aligned} \right] \alpha^*(TM)$$

$$= R(\partial_{s_1}, \partial_t) \quad \text{on } \alpha^*(TM) \quad \left. \begin{aligned} & \partial_t, \partial_{s_1} \in \Gamma(S, TS) \\ & \partial_t \alpha \in \Gamma(S, \underline{\alpha^*(TM)}) \end{aligned} \right\}$$

$$\left. \begin{aligned} & \partial_t \alpha \in \Gamma(S, \underline{\alpha^*(TM)}). \end{aligned} \right\}$$



$$\downarrow = - \int_0^1 \left\langle \partial_{s_2} \alpha, \left(\nabla_{\partial_t} \underbrace{\nabla_{\partial_{s_1}}}_{\nabla_{\partial_t}^2} + R(\partial_{s_1}, \partial_t) \right) \cdot \partial_t \alpha \right\rangle dt.$$

$E_{**}(\partial_{s_1} \alpha, \partial_{s_2} \alpha)$

$$= - \int_0^1 \left\langle \partial_{s_2} \alpha, \nabla_{\partial_t} \nabla_{\partial_t} \cdot \partial_{s_1} \alpha + \underbrace{R(\partial_{s_1}, \partial_t) \cdot \partial_t \alpha}_{\nabla_{\partial_t}^2} \right\rangle dt.$$

$E_{**}(\delta_1 \alpha, \delta_2 \alpha)$

$$= - \int_0^1 \left\langle \delta_2 \alpha, \underbrace{\nabla_{\partial_t}^2 \cdot \delta_1 \alpha}_{\nabla_{\partial_t}^2 \cdot \delta_1 \alpha} + \underbrace{R(\delta_1 \alpha, \dot{r}) \cdot \dot{r}}_{R(\delta_1 \alpha, \dot{r}) \cdot \dot{r}} \right\rangle dt$$

$$\underline{E_{**}(\delta_1 \alpha, \delta_2 \alpha)} = E_{**}(\delta_2 \alpha, \delta_1 \alpha).$$

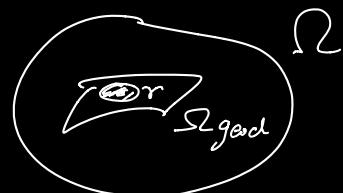
Jacobi Field. : $\Omega := \{ \gamma : [0, 1] \rightarrow M \text{ , sm} \}$.

$$\Omega_{\text{geod}} \subset \Omega \quad T\Omega_{\text{geod}} = ?$$

Fix $\gamma \in \Omega_{\text{geod}}$.

Consider a family of geodesics.

$$\alpha_s(t), \quad s \in (-\varepsilon, \varepsilon).$$



Prop : $\delta \alpha := \frac{d}{ds} \Big|_{s=0} \alpha_s(t)$ satisfy.

$$\nabla_{\partial_t}^2 \delta \alpha = -R(\delta \alpha, \dot{r}) \dot{r}$$

Pf : $\nabla_{\partial_t} \cdot \nabla_{\partial_t} \cdot \partial_s \alpha$

$$= \nabla_{\partial_t} \nabla_{\partial_s} \partial_t \alpha = (R(\partial_t, \partial_s) + \nabla_{\partial_s} \nabla_{\partial_t}) \partial_t \alpha.$$

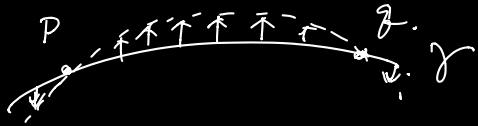
$$= R(\partial_t, \partial_s) \cdot \partial_t \alpha + \underbrace{\nabla_{\partial_s} (\nabla_{\partial_t} \partial_t \alpha)}_{\equiv 0} \quad \forall s \in (-\varepsilon, \varepsilon)$$

$$= -R(\partial_s, \partial_t) \partial_t \alpha. \quad \square$$

- Def: let γ be a geodesic.
- let $J \in "P(\gamma, TM|_{\gamma})"$. a tangent v.f. along γ . $J(t) \in T_{\gamma(t)} M$.
 $t \in [0, 1]$.
- J is a Jacobi field, if
 $\nabla^2 J + R(J, \dot{\gamma}) \dot{\gamma} = 0$. --- Jacobi Eq.

- Cop: J is a Jacobi field, iff.
 $E_{**}(J, -) = 0$.
- Def: (Conjugate points.) let γ be a geodesic.
we say $p, q \in \gamma$ are conjugate points,
if $\exists J$ Jacobi field, s.t. $J(p) = 0, J(q) = 0$.

Ex:

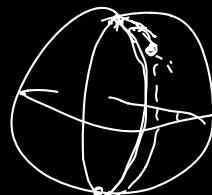
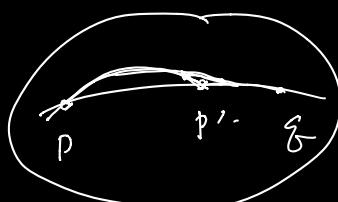


Ex: S^2 : antipodal points are conjugate points.



①. If γ is a geodesic from p to q . that has point $p' \in \text{int}(\gamma)$, s.t. (p, p') are conjugate

then. γ is not a minimizing geodesic.



② If we have sectional curvature non-positive, then
there are no conjugate points along any γ .

proof by contradiction



$$\langle J, \nabla_{\dot{\gamma}}^2 J + R(\gamma, \dot{\gamma}) \dot{\gamma} \rangle = 0.$$

$$\langle J, \nabla_{\dot{\gamma}}^2 J \rangle = - \underbrace{\langle R(\gamma, \dot{\gamma}) \dot{\gamma}, J \rangle}_{\text{sectional curvature}}$$

$$- \int |\nabla_t J|^2 dt \geq 0$$

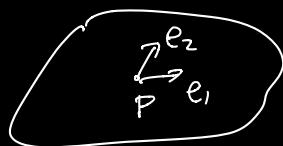
$$\Rightarrow \int |\nabla_t J|^2 dt = 0$$

$$\nabla_t J = 0.$$

$$J(p) = 0, J(q) = 0.$$

$$\Rightarrow J(t) = 0 \quad \forall t$$

$$\langle R(x, Y) Z, W \rangle.$$



$e_1 \perp e_2$
 $\|e_1\|^2 = \|e_2\| \approx 1$

$$K(e_1, e_2) := \underbrace{\langle R(e_1, e_2) e_2, e_1 \rangle}_{\text{sectional curvature at pt p}} , \text{ sectional curvature at pt p}$$

in the 2-plane span (e_1, e_2)