

## Discussion:

### Conics:

Solns to quadratic expressions

$$ax_1^2 + 2bx_1x_2 + cx_2^2 + dx_1 + ex_2 + f = 0$$

QF

$$x_1^2 + x_2^2 = x_3^2$$

$$x_3 = ax_1 + bx_2$$

LF



Principal Axis Theorem: Any QF in 2 variables has two perpendicular axes

Orthogonal Diagonalization Theorem: Any QF can be expressed as  $Ax_1^2 + Bx_2^2$  in a suitable coordinate system.

ODT  $\Rightarrow$  PAT

Corollary: Any QF can be expressed in the "normal form"

$$x_1^2 + x_2^2, x_1^2 - x_2^2, -x_1^2 - x_2^2, x_1^2, x_2^2, 0$$



Discussion:

## Determinants

$$\det: M_n(K) \rightarrow K$$

1)  $\det(I) = 1$

2) If  $B = A$  except  $\text{row}_i(B) = c \cdot \text{row}_i(A)$   
 $\det(B) = c \cdot \det(A)$

3)  $A = B + C$  except in row  $i$  we have  
 $\text{row}_i(A) = \text{row}_i(B) + \text{row}_i(C)$   
 $\det(A) = \det(B) + \det(C)$

4) If  $B$  arises from  $A$  by swapping 2 rows, then  $\det(B) = -\det(A)$

Thm a) The determinant of a matrix with a row of all zeroes is 0

b) with two identical rows is 0

c) with one row a multiple of another row is 0

d) If a multiple of one row of a matrix is added to another, the determinant remains the same

Thm: Uniqueness of the determinant

Proof: Let  $A$  be a matrix with at least one non-zero entry in each row. By multilinearity we know:

$$\det(A) = \det(A_1) + \dots + \det(A_n)$$

where  $A_j$  is the matrix identical to  $A$  except in the  $j$ th row, it is all zeroes except for the  $j$ th element