

Peng Zhou office hour: Tue 12:30 - 13:30
Evans 753

Linear Algebra \rightarrow formal structures of Math

\hookrightarrow Linear operations: $\times, +$

How diff. Eq. relates to linear algebra

e.g. $f''(x) = f(x)$

solution is linear combination of e^x and e^{-x}

Vectors \rightarrow magnitude & direction
column matrix
an element for vector space

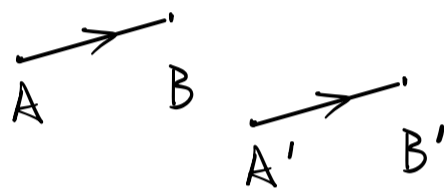
Vectors on a plane

\rightarrow directed segments \vec{AB}

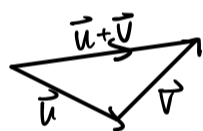
\rightarrow translation: move the endpoints

vector is an equivalence class of directed segment

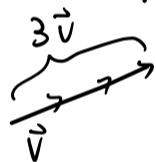
2 directed segments differ by translation \Rightarrow same vector



Vectors addition



scalar multiplication



linear combinations

\vec{v}, \vec{w} are vectors

$a, b \in \mathbb{R}$

$a\vec{v} + b\vec{w}$ is well defined.

- Inner product / dot product $\vec{v} \cdot \vec{u}$

given 2 vectors \vec{v} and \vec{u}

we define $\langle \vec{v}, \vec{u} \rangle$

$$\langle \vec{v}, \vec{u} \rangle = |\vec{v}| |\vec{u}| \cos \theta$$

linear operation

\hookrightarrow structure of scalar multiplication & addition

e.g. $\langle \vec{v}_1 + \vec{v}_2, \vec{u} \rangle$

$$= \langle \vec{v}_1, \vec{u} \rangle + \langle \vec{v}_2, \vec{u} \rangle$$

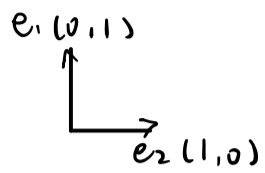
$$\langle 3\vec{v}, \vec{w} \rangle = 3 \langle \vec{v}, \vec{w} \rangle$$

$$\langle \vec{u}, \vec{u} \rangle = |\vec{u}|^2$$

$$\langle \vec{u}_1 + \vec{u}_2, \vec{v}_1 + \vec{v}_2 \rangle$$

$$\cos \theta = \frac{\langle \vec{u}, \vec{v} \rangle}{\|\vec{u}\| \cdot \|\vec{v}\|} = \langle \vec{u}_1, \vec{v}_1 \rangle + \langle \vec{u}_2, \vec{v}_2 \rangle + \langle \vec{u}_1, \vec{v}_2 \rangle + \langle \vec{u}_2, \vec{v}_1 \rangle$$

Basis vectors



Any other vectors can be written in the linear combination of e_1 and e_2

$(e_1, e_2) \Rightarrow$ ortho normal spaces
 $e_1 \perp e_2$ $\|e_1\| = \|e_2\| = 1$

Claim: $\vec{v} = \langle \vec{v}, e_1 \rangle e_1 + \langle \vec{v}, e_2 \rangle e_2$

Suppose $v = a_1 e_1 + a_2 e_2$

apply $\langle \cdot, e_1 \rangle$ to both sides

$$\begin{aligned} \langle \vec{v}, e_1 \rangle &= \langle a_1 e_1 + a_2 e_2, e_1 \rangle \\ &= \langle a_1 e_1, e_1 \rangle + \langle a_2 e_2, e_1 \rangle \\ &= a_1 \|e_1\|^2 + a_2 \cdot 0 \\ &= a_1 \end{aligned}$$

Skewed basis on \mathbb{R}^2

if (E_1, E_2) in \mathbb{R}^2 satisfies $\forall v = a_1 E_1 + a_2 E_2$
 then (E_1, E_2) is a basis

Coordinates: given a basis (E_1, E_2)

we say vector \vec{v} has coordinate (a_1, a_2)
 if $\vec{v} = a_1 \vec{E}_1 + a_2 \vec{E}_2$

